

Homework 1 Solution

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1. Given $f = z^3 + zx + x^4y - 3y = 0$
 (a) $\therefore \frac{\partial f}{\partial x} = z + 4x^3y, \frac{\partial f}{\partial y} = x^4 - 3, \frac{\partial f}{\partial z} = 3z^2 + x$
 $\therefore \frac{\partial z}{\partial x}|_y = -\frac{\frac{\partial f}{\partial x}}{\frac{\partial f}{\partial z}} = -\frac{z+4x^3y}{3z^2+x}, \frac{\partial z}{\partial y}|_x = -\frac{\frac{\partial f}{\partial y}}{\frac{\partial f}{\partial z}} = -\frac{x^4-3}{3z^2+x}$
 (b) For $(x, y) = (1, 2) \Rightarrow z = -0.6894 \pm 1.5575i, 1.3788,$
 $\frac{\partial z}{\partial x}|_y = -\frac{z+8}{3z^2+1}, \frac{\partial z}{\partial y}|_x = \frac{2}{3z^2+1}$

8. Find the length of the shortest curve between two points with cylindrical coordinates $(r, \theta, z) = (a, 0, 0)$ and $(r, \theta, z) = (a, \Theta, Z)$ along the surface of the cylinder $r = a$.

$$\begin{cases} \xi^1 = r \cos \theta \\ \xi^2 = r \sin \theta \\ \xi^3 = z \end{cases} \text{ . So the Jacobian matrix } J = \begin{pmatrix} \cos \theta & -r \sin \theta & 0 \\ \sin \theta & r \cos \theta & 0 \\ 0 & 0 & 1 \end{pmatrix}, \text{ the metric}$$

$$\text{tensor } G = J^T \cdot J = \begin{pmatrix} 1 & 0 & 0 \\ 0 & r^2 & 0 \\ 0 & 0 & 1 \end{pmatrix}.$$

$$\text{So the distance between } (a, 0, 0) \text{ and } (a, \Theta, Z) \text{ is } \begin{pmatrix} 0 & \Theta & Z \end{pmatrix} \cdot G \cdot \begin{pmatrix} 0 \\ \Theta \\ Z \end{pmatrix} = \sqrt{r^2\Theta^2 + Z^2}$$

10. Given $I = \int_0^1 (x^2y'^2 + 40x^4y)dx$, using Euler equation, get $40x^4 - \frac{d}{dx}(2x^2y') = 0 \Rightarrow 2x^2y' = 8x^5 + c_1$. For $x \neq 0$, get $y' = 4x^3 + \frac{c_1}{2x^2} \Rightarrow y = x^4 - \frac{c_1}{2x} + c_2$. For $x = 0 \Rightarrow c_1 = 0$. Given $y(0) = 0, y(1) = 1 \Rightarrow c_2 = 0 \Rightarrow$ the extremum $y = x^4$

13. Given $u = \frac{x+y}{x-y}, v = \frac{xy}{(x-y)^2}$,

$$\frac{\partial(u,v)}{\partial(x,y)} = \begin{vmatrix} \frac{\partial u}{\partial x} & \frac{\partial u}{\partial y} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} \end{vmatrix} = \begin{vmatrix} -\frac{2y}{(x-y)^2} & \frac{2x}{(x-y)^2} \\ -\frac{y(x+y)}{(x-y)^3} & \frac{x(x+y)}{(x-y)^3} \end{vmatrix} = 0 \Rightarrow u, v \text{ dependent}$$

16. Given $\begin{cases} \xi^1 = \cosh x^1 \cos x^2 \\ \xi^2 = \sinh x^1 \sin x^2 \\ \xi^3 = x^3 \end{cases}$

$$\bullet J = \begin{pmatrix} \sinh x^1 \cos x^2 & -\cosh x^1 \sin x^2 & 0 \\ \cosh x^1 \sin x^2 & \sinh x^1 \cos x^2 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$\bullet G = J^T \cdot J = \begin{pmatrix} \frac{\cosh 2x^1 - \cos 2x^2}{2} & 0 & 0 \\ 0 & \frac{\cosh 2x^1 - \cos 2x^2}{2} & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$\bullet \therefore \cosh x^1 \cdot \sinh x^1 = 1, \\ \left(\frac{\xi^1}{\cosh x^1}\right)^2 - \left(\frac{\xi^2}{\sinh x^1}\right)^2 = \cos 2x^2 = \sqrt{1 - \xi^1 \xi^2}$$

$$\left(\frac{\xi^1}{\cosh x^1}\right)^2 + \left(\frac{\xi^2}{\sinh x^1}\right)^2 = 1,$$

Inverse Transformation is

$$\begin{cases} x^1 = \operatorname{arccosh} \frac{\xi^1}{\cos x^2} = \operatorname{arccosh} \frac{\xi^1}{\cos(\frac{1}{2} \arcsin 2\xi^1 \xi^2)} \\ x^2 = \frac{1}{2} \arcsin 2\xi^1 \xi^2 \\ x^3 = \xi^3 \end{cases}$$

- As for plot, if $x^1 = \text{constant}$, $\frac{\xi^2}{\xi^1} = c_1 \tan x^2$, where $c_1 = \tanh x^1$; if $x^2 = \text{constant}$, $\frac{\xi^2}{\xi^1} = c_2 \tanh x^1$, where $c_2 = \tan x^2$

17. Similar with the example 1.6 in textbook.

$$\because \nabla \cdot u = \frac{\partial u^i}{\partial \xi^i} + \Gamma_{il}^i u^l$$

$$\begin{aligned} \Gamma_{il}^i u^l &= \frac{\partial^2 \xi^p}{\partial x^i \partial x^l} \frac{\partial x^i}{\partial \xi^p} u^l \\ &= \frac{\partial^2 \xi^1}{\partial x^1 \partial x^1} \frac{\partial x^1}{\partial \xi^1} u^1 + \frac{\partial^2 \xi^1}{\partial x^1 \partial x^2} \frac{\partial x^1}{\partial \xi^1} u^2 + \frac{\partial^2 \xi^1}{\partial x^2 \partial x^1} \frac{\partial x^2}{\partial \xi^1} u^1 + \frac{\partial^2 \xi^1}{\partial x^2 \partial x^2} \frac{\partial x^2}{\partial \xi^1} u^2 + \\ &\frac{\partial^2 \xi^2}{\partial x^1 \partial x^1} \frac{\partial x^1}{\partial \xi^2} u^1 + \frac{\partial^2 \xi^2}{\partial x^1 \partial x^2} \frac{\partial x^1}{\partial \xi^2} u^2 + \frac{\partial^2 \xi^2}{\partial x^2 \partial x^1} \frac{\partial x^2}{\partial \xi^2} u^1 + \frac{\partial^2 \xi^2}{\partial x^2 \partial x^2} \frac{\partial x^2}{\partial \xi^2} u^2 \end{aligned}$$

and

$$\begin{aligned} \frac{\partial^2 \xi^1}{\partial x^1 \partial x^1} &= \cosh x^1 \cos x^2 \\ \frac{\partial^2 \xi^1}{\partial x^1 \partial x^2} &= -\sinh x^1 \sin x^2 = \frac{\partial^2 \xi^1}{\partial x^2 \partial x^1} \\ \frac{\partial^2 \xi^1}{\partial x^2 \partial x^2} &= -\cosh x^1 \cos x^2 \\ \frac{\partial^2 \xi^2}{\partial x^1 \partial x^1} &= \sinh x^1 \sin x^2 \\ \frac{\partial^2 \xi^2}{\partial x^1 \partial x^2} &= \cosh x^1 \cos x^2 = \frac{\partial^2 \xi^2}{\partial x^2 \partial x^1} \\ \frac{\partial^2 \xi^2}{\partial x^2 \partial x^2} &= -\sinh x^1 \sin x^2 \end{aligned}$$

$$\begin{aligned} \frac{\partial x^1}{\partial \xi^1} &= \frac{\sec(\frac{1}{2} \arcsin(2\xi^1 \xi^2)) + \xi^1 \xi^2 \sec(\frac{1}{2} \arcsin(2\xi^1 \xi^2)) \tan(\frac{1}{2} \arcsin(2\xi^1 \xi^2))}{\sqrt{1-4(\xi^1 \xi^2)^2}} \\ \frac{\partial x^2}{\partial \xi^1} &= \frac{\sqrt{-1+\xi^1 \sec(\frac{1}{2} \arcsin(2\xi^1 \xi^2))} \sqrt{1+\xi^1 \sec(\frac{1}{2} \arcsin(2\xi^1 \xi^2))}}{(\xi^1)^2 \sec(\frac{1}{2} \arcsin(2\xi^1 \xi^2)) \tan(\frac{1}{2} \arcsin(2\xi^1 \xi^2))} \\ \frac{\partial x^1}{\partial \xi^2} &= \frac{\xi^2}{\sqrt{1-4(\xi^1 \xi^2)^2}} \\ \frac{\partial x^2}{\partial \xi^2} &= \frac{\xi^1}{\sqrt{1-4(\xi^1 \xi^2)^2}} \end{aligned}$$

18. Cylindrical coordinates $\begin{cases} \xi^1 &= x^1 \cos x^2 \\ \xi^2 &= x^1 \sin x^2 \\ \xi^3 &= x^3 \end{cases}$, the contravariant velocity vector is $U^i =$

$$\begin{aligned} \frac{\partial \xi^i}{\partial x^j} u^l, \text{ the covariant derivative of this vector in cylindrical coordinates is } W_j^i &= \frac{\partial U^i}{\partial x^j} = \\ \frac{\partial}{\partial x^j} (\frac{\partial \xi^i}{\partial x^l} u^l) &= \frac{\partial^2 \xi^i}{\partial x^j \partial x^l} u^l \\ &= \frac{\partial^2 \xi^1}{\partial x^1 \partial x^1} u^1 + \frac{\partial^2 \xi^1}{\partial x^1 \partial x^2} u^2 + \frac{\partial^2 \xi^1}{\partial x^2 \partial x^1} u^1 + \frac{\partial^2 \xi^1}{\partial x^2 \partial x^2} u^2 + \frac{\partial^2 \xi^2}{\partial x^1 \partial x^1} u^1 + \frac{\partial^2 \xi^2}{\partial x^1 \partial x^2} u^2 + \frac{\partial^2 \xi^2}{\partial x^2 \partial x^1} u^1 + \frac{\partial^2 \xi^2}{\partial x^2 \partial x^2} u^2 \\ &= (\cos x^2 - \sin x^2) u^1 + (\cos x^2 - \sin x^2 - x^1 (\cos x^2 + \sin x^2)) u^2 \end{aligned}$$

$$\text{ex. Given } \begin{cases} \theta_1 &= \sqrt{x^1 + x^2 + x^3} \\ \theta_2 &= \cos^{-1} \left(\frac{x_3}{\sqrt{x_1^2 + x_2^2 + x_3^2}} \right) \\ \theta_3 &= \tan^{-1} \left(\frac{x_2}{x_1} \right) \end{cases} \text{ and the inverse } \begin{cases} x_1 &= \theta_1 \sin \theta_2 \cos \theta_3 \\ x_2 &= \theta_1 \sin \theta_2 \sin \theta_3 \\ x_3 &= \theta_1 \cos \theta_2 \end{cases}$$

$$\text{The Jacobian matrix } J = \frac{\partial(x_1, x_2, x_3)}{\partial(\theta_1, \theta_2, \theta_3)} = \begin{pmatrix} \sin \theta_2 \cos \theta_3 & \theta_1 \cos \theta_2 \cos \theta_3 & -\theta_1 \sin \theta_2 \sin \theta_3 \\ \sin \theta_2 \sin \theta_3 & \theta_1 \cos \theta_2 \sin \theta_3 & \theta_1 \sin \theta_2 \cos \theta_3 \\ \cos \theta_2 & -\theta_1 \sin \theta_2 & 0 \end{pmatrix},$$

$$\text{the metric tensor } G = J^T \cdot J = \begin{pmatrix} 1 & 0 & 0 \\ 0 & \theta_1^2 & 0 \\ 0 & 0 & \theta_1^2 \sin^2 \theta_2 \end{pmatrix}$$