Friday, October 19

Reception: 6:30-8:00pm

Saturday, October 20

Session 1: 8:30-9:00, Introduction and Welcome

Session 2: 9:00-11:00, Fundamentals

- Xenofon Koutsoukos, Resilient Cooperative Control of Cyber-Physical Systems
- Panos Antsaklis, Bill Goodwine and Vijay Gupta, Passivity and Symmetry in the Control of Cyber-Physical Systems
- Karl-Erik Årzén, Simulation of Cyber-Physical Control Systems
- Stefan Kowalewski, Architectural Support for Agile Control Design in CPS
- John S. Baras, Components, Compositionality and Architectures for Networked CPS

Coffee Break: 11:00-11:20

Session 3: 11:20-1:00, Applications

- Carlos Canudas-de-Wit, CPS in Intelligent Transportation Systems: the Grenoble south ring show case
- Eduardo F. Camacho, Control of Solar Thermal Plants
- João Sousa, Coordination Challenges in Networked Vehicle Systems: Are We Missing Something?
- Malcolm Smith, Classical Network Synthesis Revisited

Lunch Break: 1:00-2:00

Session 4: 2:00-4:00, Panel Discussion

Tentative Panel List:

- Alessandro Astolfi
- John S. Baras
- Sandra Hirche
- Karl Erik Johansson
- Francoise Lamnabhi-Lagarrigue

Coffee Break: 4:00-4:30

Session 5: 4:30-6:30, Control I

- Thomas Parisini and Marios Polycarpou, Towards Safe and Reliable CPS: A Learning-Based Distributed Fault-Diagnosis Approach
- Joerg Raisch, Control Hierarchies and Tropical Algebras
- Jan Maciejowski, Some New Developments in Model Predictive Control
- Kostas Kyriakopoulos, A Framework for Aperiodic Model Predictive Control
- Antonio Bicchi, Trading off Feedforward and Feedback, Remote and Local in the Control of Complex Interconnected Plants

Reception: 6:30-8:00

Sunday, October 21

Session 6: 9:00-11:00, Control II

- Arjan van der Schaft, Bisimulation Theory for Multi-Modal Physical Systems
- Claudio De Persis, Coordination Control in a Cyberphysical Environment
- Marika Di Benedetto, Analysis and Control of Networked Embedded Systems
- Eric Kerrigan, Number Representations for Embedding Optimization Algorithms in Cyber-Physical Systems
- Maurice Heemels, Event-Triggered and Self-Triggered Control Design with Guaranteed Performance