

1. a. diagonalization.
 Number 1: $\tilde{x}' = \begin{pmatrix} 2 & -1 \\ 3 & -2 \end{pmatrix} \tilde{x} + \begin{pmatrix} t \\ e^t \end{pmatrix}$

$$\begin{vmatrix} 2-\lambda & -1 \\ 3 & -2-\lambda \end{vmatrix} = 0 \Rightarrow \lambda_1 = 1 \quad \lambda_2 = -1$$

when $\lambda_1 = 1$,

$$\begin{pmatrix} 2-\lambda_1 & -1 \\ 3 & -2-\lambda_1 \end{pmatrix} \begin{pmatrix} \tilde{x}_1^{(1)} \\ \tilde{x}_2^{(1)} \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \Rightarrow \begin{pmatrix} 1 & -1 \\ 3 & -3 \end{pmatrix} \begin{pmatrix} \tilde{x}_1^{(1)} \\ \tilde{x}_2^{(1)} \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\Rightarrow \tilde{x}^{(1)} = \begin{pmatrix} \tilde{x}_1^{(1)} \\ \tilde{x}_2^{(1)} \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

when $\lambda_2 = -1$,

$$\begin{pmatrix} 2-\lambda_2 & -1 \\ 3 & -2-\lambda_2 \end{pmatrix} \begin{pmatrix} \tilde{x}_1^{(2)} \\ \tilde{x}_2^{(2)} \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \Rightarrow \begin{pmatrix} 3 & -1 \\ 3 & -1 \end{pmatrix} \begin{pmatrix} \tilde{x}_1^{(2)} \\ \tilde{x}_2^{(2)} \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\Rightarrow \tilde{x}^{(2)} = \begin{pmatrix} \tilde{x}_1^{(2)} \\ \tilde{x}_2^{(2)} \end{pmatrix} = \begin{pmatrix} 1 \\ 3 \end{pmatrix}$$

The general solution of the homogeneous system is:
 $\tilde{x} = c_1 \begin{pmatrix} 1 \\ 1 \end{pmatrix} e^t + c_2 \begin{pmatrix} 3 \\ 1 \end{pmatrix} e^{-t}$

upon normalizing $\tilde{q}^{(1)}$ and $\tilde{q}^{(2)}$,

$$\tilde{T} = \begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{10}} \\ \frac{1}{\sqrt{2}} & \frac{3}{\sqrt{10}} \end{pmatrix} \Rightarrow \tilde{T}^{-1} = \begin{pmatrix} \frac{3\sqrt{2}}{2} & -\frac{1}{2\sqrt{2}} \\ -\frac{1}{2\sqrt{2}} & \frac{1}{2\sqrt{10}} \end{pmatrix}$$

$$\tilde{D} = \tilde{T}^{-1} A \tilde{T} = \begin{pmatrix} -\frac{1}{2\sqrt{10}} & -\frac{1}{2\sqrt{2}} \\ \frac{2}{\sqrt{10}} & \frac{2}{\sqrt{2}} \end{pmatrix} \begin{pmatrix} 3 & -2 \\ 2 & -1 \end{pmatrix} \begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{10}} \\ \frac{1}{\sqrt{2}} & \frac{3}{\sqrt{10}} \end{pmatrix}$$

$$= \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$\left(k_1 = \frac{\sqrt{2}}{5}, k_2 = -\frac{\sqrt{2}}{5} \right)$$

$$+ \begin{pmatrix} 2 \\ 1 \end{pmatrix} t$$

$$= k_1 \begin{pmatrix} 1 \\ 1 \end{pmatrix} e^t + k_2 \begin{pmatrix} 1 \\ 3 \end{pmatrix} e^{-t} + \begin{pmatrix} 1 \\ 3 \end{pmatrix} e^{\frac{2}{3}t} + \begin{pmatrix} 1 \\ 1 \end{pmatrix} t e^t$$

$$\Rightarrow \tilde{x} = \tilde{I} \tilde{y} = \tilde{x} \Rightarrow \begin{pmatrix} \frac{\sqrt{2}}{5} \\ \frac{\sqrt{2}}{3} t e^t + (4 - \frac{4}{3\sqrt{2}}) e^t + 2\sqrt{2} t - \sqrt{2} + \frac{\sqrt{2}}{3} e^{-t} \end{pmatrix} = \begin{pmatrix} \frac{\sqrt{2}}{5} \\ \frac{\sqrt{2}}{3} t e^t + (4 - \frac{4}{3\sqrt{2}}) e^t + \sqrt{2} t + \frac{\sqrt{2}}{3} e^{-t} \end{pmatrix} \begin{pmatrix} y_1' + \frac{\sqrt{2}}{5} \\ y_2' + \frac{\sqrt{2}}{3} \end{pmatrix}$$

$$\Rightarrow y_1' = \frac{\sqrt{2}}{3} t e^t + \frac{\sqrt{2}}{5} + \frac{\sqrt{2}}{3} t + \frac{\sqrt{2}}{5} + 4 e^{-t} \quad y_2' = -\frac{\sqrt{2}}{10} e^t + \frac{\sqrt{2}}{10} t - \frac{\sqrt{2}}{2} + 6 e^{-t}$$

$$\begin{cases} y_1' + y_2 = -\frac{\sqrt{2}}{10} e^t + \frac{\sqrt{2}}{10} t \\ y_1' - y_2 = \frac{\sqrt{2}}{3} e^t - \frac{\sqrt{2}}{3} t \end{cases}$$

Thus, $y_1' - y_2 = \frac{\sqrt{2}}{3} e^t - \frac{\sqrt{2}}{3} t$

$$\tilde{y}' = \tilde{P} \tilde{y} + \tilde{I}^{-1} \tilde{g}(t) = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \tilde{y} + \frac{2}{\sqrt{2}} \begin{pmatrix} 3 e^t t \\ -\sqrt{2} e^t + \sqrt{2} t \end{pmatrix}$$

$$\tilde{y}' = \tilde{P} \tilde{y} + \tilde{I}^{-1} \tilde{g}(t) = \begin{pmatrix} -\frac{\sqrt{2}}{10} & \frac{2}{\sqrt{2}} \\ \frac{2}{\sqrt{2}} & -\frac{\sqrt{2}}{10} \end{pmatrix} \begin{pmatrix} t \\ e^t \end{pmatrix} = \begin{pmatrix} \frac{2}{\sqrt{2}} (-e^t + t) \\ \frac{\sqrt{2}}{2} (3 e^t t) \end{pmatrix}$$

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Number 4:

$$\vec{x}' = \begin{pmatrix} 1 & 1 \\ 4 & -2 \end{pmatrix} \vec{x} + \begin{pmatrix} 0 \\ -2e^t \end{pmatrix}$$

$$\begin{vmatrix} 1-r & 1 \\ 4 & -2-r \end{vmatrix} = 0 \Rightarrow r=2 \quad r=-3$$

When $r=2$,

$$\begin{pmatrix} 1-r & 1 \\ 4 & -2-r \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \Rightarrow \begin{pmatrix} -1 & 1 \\ 4 & -4 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\Rightarrow \vec{x}^{(1)} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

When $r=-3$,

$$\begin{pmatrix} 1-r & 1 \\ 4 & -2-r \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \Rightarrow \begin{pmatrix} 4 & 1 \\ 4 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\vec{x}^{(2)} = \begin{pmatrix} 1 \\ -4 \end{pmatrix}$$

The general solution of the homogeneous system is:

$$\vec{x} = c_1 \begin{pmatrix} 1 \\ 1 \end{pmatrix} e^{2t} + c_2 \begin{pmatrix} 1 \\ -4 \end{pmatrix} e^{-3t}$$

upon normalizing $\vec{x}^{(1)}$ and $\vec{x}^{(2)}$,

$$\vec{u} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \end{pmatrix} \quad \vec{v} = \frac{1}{5} \begin{pmatrix} 1 \\ -4 \end{pmatrix} \Rightarrow \vec{T}^{-1} = \frac{1}{5} \begin{pmatrix} 4\sqrt{2} & \sqrt{2} \\ \sqrt{17} & -\sqrt{17} \end{pmatrix}$$

$$\vec{D} = \vec{T}^{-1} \vec{A} \vec{T} = \frac{1}{5} \begin{pmatrix} 4\sqrt{2} & \sqrt{2} \\ \sqrt{17} & -\sqrt{17} \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 4 & -2 \end{pmatrix} \begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{17}} \\ -\frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{17}} \end{pmatrix} = \begin{pmatrix} 2 & 0 \\ 0 & -3 \end{pmatrix}$$

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$$(k_1 = \frac{\sqrt{2}}{4}, k_2 = \frac{\sqrt{17}}{4})$$

$$= k_1 \begin{pmatrix} 1 \\ 1 \end{pmatrix} e^{2t} + k_2 \begin{pmatrix} 1 \\ -4 \end{pmatrix} e^{-3t} + \begin{pmatrix} \frac{2}{1} e^t \\ -e^{-2t} \end{pmatrix}$$

$$= \begin{bmatrix} -e^{-2t} + \frac{\sqrt{2}}{4} e^{2t} - \frac{\sqrt{17}}{4} e^{-3t} \\ \frac{2}{1} e^t + \frac{\sqrt{2}}{4} e^{2t} + \frac{\sqrt{17}}{4} e^{-3t} \end{bmatrix}$$

$$= \begin{bmatrix} -\frac{1}{5} e^{-2t} + \frac{2}{5} e^t + \frac{\sqrt{2}}{4} e^{2t} - \frac{5}{4} e^{-2t} - \frac{5}{2} e^{-\frac{3}{2}t} - \frac{\sqrt{17}}{4} e^{-3t} \\ -\frac{1}{5} e^{-2t} + \frac{2}{5} e^t + \frac{\sqrt{2}}{4} e^{2t} + \frac{1}{5} e^{-2t} + \frac{10}{1} e^t + \frac{\sqrt{17}}{4} e^{-3t} \end{bmatrix}$$

$$\Rightarrow \tilde{x} = \tilde{I} \tilde{y} = \begin{pmatrix} \frac{\sqrt{2}}{4} & \frac{\sqrt{17}}{4} \\ \frac{\sqrt{2}}{4} & -\frac{\sqrt{17}}{4} \end{pmatrix} \begin{pmatrix} y_1 \\ y_2 \end{pmatrix} = \begin{pmatrix} \frac{y_1}{4} + \frac{\sqrt{17}}{4} y_2 \\ \frac{y_1}{4} - \frac{\sqrt{17}}{4} y_2 \end{pmatrix}$$

$$y_2 = \frac{5}{\sqrt{17}} e^{-2t} + \frac{10}{\sqrt{17}} e^t + c_2 e^{-3t}$$

$$\Rightarrow y_1 = -\frac{5}{\sqrt{2}} e^{-2t} + \frac{5}{2\sqrt{2}} e^t + c_1 e^{2t}$$

$$\left\{ \begin{aligned} y_1' + 3y_2 &= \frac{5}{\sqrt{17}} (e^{-2t} + 2e^t) \end{aligned} \right.$$

$$\left\{ \begin{aligned} y_1' - 2y_1 &= \frac{5}{2\sqrt{2}} (2e^{-2t} - e^t) \end{aligned} \right.$$

Thus,

$$\tilde{y}' = \tilde{D} \tilde{y} + \tilde{I}^T \tilde{g}(t) = \begin{pmatrix} 2 & 0 \\ 0 & -3 \end{pmatrix} \tilde{y} + \frac{1}{5} \begin{pmatrix} 4\sqrt{2} e^{-2t} - 2\sqrt{2} e^t \\ \sqrt{17} e^{-2t} + 2\sqrt{17} e^t \end{pmatrix}$$

$$\tilde{I}^T \tilde{g}(t) = \frac{1}{5} \begin{pmatrix} 4\sqrt{2} & \sqrt{2} \\ \sqrt{17} & -\sqrt{17} \end{pmatrix} \begin{pmatrix} e^{-2t} \\ -2e^t \end{pmatrix} = \frac{1}{5} \begin{pmatrix} 4\sqrt{2} e^{-2t} - 2\sqrt{2} e^t \\ \sqrt{17} e^{-2t} + 2\sqrt{17} e^t \end{pmatrix}$$

b. undetermined coefficients.

Number 1: $\vec{x}' = \begin{pmatrix} 2 & -1 \\ 3 & -2 \end{pmatrix} \vec{x} + \begin{pmatrix} e^t \\ t \end{pmatrix}$

we write $\vec{g}(t)$ in the form $\vec{g}(t) = \begin{pmatrix} 0 \\ 1 \end{pmatrix} e^t + \begin{pmatrix} 0 \\ 1 \end{pmatrix} t$.

Then we assume that

$$\vec{x} = \vec{v}(t) = \vec{a} t e^t + \vec{b} e^t + \vec{c} t + \vec{d}$$

Substituting above eq into the differential equation,

$$\begin{cases} A \vec{a} = \vec{a} \\ A \vec{b} = \vec{a} + \vec{b} - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \\ A \vec{c} = -\begin{pmatrix} 0 \\ 1 \end{pmatrix} \\ A \vec{d} = \vec{c} \end{cases} \Rightarrow \vec{a} = \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} \quad \text{--- (1)}$$

$$\begin{cases} A \vec{b} = \vec{a} + \vec{b} - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \quad \text{--- (2)} \\ A \vec{c} = -\begin{pmatrix} 0 \\ 1 \end{pmatrix} \quad \text{--- (3)} \\ A \vec{d} = \vec{c} \quad \text{--- (4)} \end{cases}$$

assume $\vec{b} = \begin{pmatrix} b_1 \\ b_2 \end{pmatrix}$.

$$\begin{aligned} \text{(2)} \Rightarrow \lambda = \frac{2}{3} &\Rightarrow \vec{a} = \begin{bmatrix} \frac{2}{3} \\ \frac{2}{3} \end{bmatrix}, \quad \vec{b} = \begin{pmatrix} 0 \\ \frac{1}{2} \end{pmatrix} \\ \text{(3)} \Rightarrow \vec{c} &= \begin{pmatrix} 2 \\ 1 \end{pmatrix} \\ \text{(4)} \Rightarrow \vec{d} &= \begin{pmatrix} 0 \\ -1 \end{pmatrix} \end{aligned}$$

finally, we obtain the particular solution:

$$\vec{x}(t) = \begin{pmatrix} \frac{2}{3} \\ \frac{2}{3} \end{pmatrix} t e^t + \begin{pmatrix} 0 \\ \frac{1}{2} \end{pmatrix} e^t + \begin{pmatrix} 2 \\ 1 \end{pmatrix} t + \begin{pmatrix} 0 \\ -1 \end{pmatrix}$$

the general solution is:

$$\vec{x} = c_1 \begin{pmatrix} 1 \\ 1 \end{pmatrix} e^t + c_2 \begin{pmatrix} 1 \\ 3 \end{pmatrix} e^{-t} + \begin{pmatrix} \frac{2}{3} \\ \frac{2}{3} \end{pmatrix} t e^t + \begin{pmatrix} 0 \\ \frac{1}{2} \end{pmatrix} e^t + \begin{pmatrix} 2 \\ 1 \end{pmatrix} t + \begin{pmatrix} 0 \\ -1 \end{pmatrix}$$

Number 4: $\tilde{x}' = \begin{pmatrix} 1 & 1 \\ 4 & -2 \end{pmatrix} \tilde{x} + \begin{pmatrix} e^{2t} \\ 0 \end{pmatrix}$

$$\tilde{y}(t) = \begin{pmatrix} e^{-2t} \\ -2e^t \end{pmatrix} = \begin{pmatrix} e^{-2t} \\ 0 \end{pmatrix} + \begin{pmatrix} 0 \\ -2 \end{pmatrix} e^t$$

~~$\lambda = -2$ is an eigenvalue of the coefficient matrix.~~
Assume that

$$\tilde{x} = \tilde{u}(t) = \tilde{a} e^{-2t} + \tilde{b} e^t + \tilde{c}$$

Substituting above eqn. to differential eqn,

$$\begin{cases} \tilde{a}\tilde{a} = -2\tilde{a} + \begin{pmatrix} -1 \\ 0 \end{pmatrix} \Rightarrow \tilde{a} = \begin{pmatrix} 0 \\ -1 \end{pmatrix} \\ \tilde{a}\tilde{b} = \tilde{b} - \begin{pmatrix} 2 \\ 0 \end{pmatrix} \Rightarrow \tilde{b} = \begin{pmatrix} 2 \\ 0 \end{pmatrix} \\ \tilde{a}\tilde{c} = 0 \Rightarrow \tilde{c} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \end{cases}$$

particular solution is:

$$\tilde{y}, \tilde{x}^* = \tilde{v}(t) = \begin{pmatrix} -1 \\ 0 \end{pmatrix} e^{-2t} + \begin{pmatrix} 2 \\ 0 \end{pmatrix} e^t$$

so, general solution:

$$\tilde{x} = c_1 \begin{pmatrix} 1 \\ 1 \end{pmatrix} e^{2t} + c_2 \begin{pmatrix} -1 \\ 1 \end{pmatrix} e^{-2t} + \begin{pmatrix} 0 \\ 2 \end{pmatrix} e^t$$

C. Variation of parameters:

Number 1: $\tilde{x}' = \begin{pmatrix} 2 & -1 \\ 3 & -2 \end{pmatrix} \tilde{x} + \begin{pmatrix} e^t \\ e^t \end{pmatrix}$

from previous calculation,

$\tilde{\Phi}(t) = \begin{pmatrix} e^t & e^{-t} \\ e^t & 3e^{-t} \end{pmatrix}$ is a fundamental matrix.

$\tilde{x} = \tilde{\Phi}(t) \tilde{u}(t)$ where $\tilde{u}(t)$ satisfies $\tilde{\Phi}'(t) \tilde{u}(t) = \tilde{g}(t)$,

$\Rightarrow \begin{cases} u_1' = \frac{2}{3} - \frac{1}{3}t e^{-t} \\ u_2' = \frac{1}{3}t e^{-t} - \frac{1}{3}e^{-2t} \end{cases}$

$\begin{pmatrix} e^t & e^{-t} \\ e^t & 3e^{-t} \end{pmatrix} \begin{pmatrix} u_1' \\ u_2' \end{pmatrix} = \begin{pmatrix} e^t \\ t \end{pmatrix}$

Hence, $u_1(t) = \frac{1}{3}t e^{-t} + \frac{2}{3}e^{-t} + \frac{2}{3}t + C_1$

$u_2(t) = \frac{1}{2}t e^t - \frac{1}{2}e^t - \frac{1}{4}e^{2t} + C_2$

and $\tilde{x} = \tilde{\Phi}(t) \tilde{u}(t) = \begin{pmatrix} e^t & e^{-t} \\ e^t & 3e^{-t} \end{pmatrix} \begin{pmatrix} \frac{1}{3}t e^{-t} + \frac{2}{3}e^{-t} + \frac{2}{3}t + C_1 \\ \frac{1}{2}t e^t - \frac{1}{2}e^t - \frac{1}{4}e^{2t} + C_2 \end{pmatrix}$

$= C_1 \begin{pmatrix} 1 \\ 1 \end{pmatrix} e^t + C_2 \begin{pmatrix} 1 \\ 3 \end{pmatrix} e^{-t} - \frac{1}{4}e^{-t} + \frac{2}{3} \begin{pmatrix} 1 \\ 1 \end{pmatrix} t e^t$

$+ \begin{pmatrix} 2 \\ 1 \end{pmatrix} t.$

Number 4: $\tilde{x}' = \begin{pmatrix} 1 & 1 \\ 4 & -2 \end{pmatrix} \tilde{x} + \begin{pmatrix} e^{-2t} \\ -2e^t \end{pmatrix}$

$$\tilde{\phi}(t) = \begin{pmatrix} e^{2t} & e^{3t} \\ e^{2t} & -4e^{-3t} \end{pmatrix}$$

$$\tilde{\phi}(t) \tilde{u}'(t) = \tilde{g}(t) \Rightarrow \begin{pmatrix} e^{2t} & e^{3t} \\ e^{2t} & -4e^{-3t} \end{pmatrix} \begin{pmatrix} u_1'(t) \\ u_2'(t) \end{pmatrix} = \begin{pmatrix} e^{-2t} \\ -2e^t \end{pmatrix}$$

$$\Rightarrow \begin{cases} u_1' = \frac{5}{4} e^{-4t} - \frac{5}{2} e^{-t} \\ u_2' = \frac{5}{1} e^t + \frac{5}{2} e^{4t} \end{cases}$$

$$\Rightarrow \begin{cases} u_1 = -\frac{5}{1} e^{-4t} + \frac{5}{2} e^{-t} + c_1 \\ u_2 = \frac{5}{1} e^t + \frac{1}{10} e^{4t} + c_2 \end{cases}$$

and $\tilde{x} = \tilde{\phi}(t) \tilde{u}(t) = c_1 \begin{pmatrix} 1 \\ 1 \end{pmatrix} e^{2t} + c_2 \begin{pmatrix} 1 \\ -4 \end{pmatrix} e^{-3t} + \begin{pmatrix} \frac{5}{1} e^{-t} \\ -2e^t \end{pmatrix}$

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2. numbers 3 by undetermined coefficients.

$$\tilde{x}' = \begin{pmatrix} 1 & -5 \\ 2 & -2 \end{pmatrix} \tilde{x} + \begin{pmatrix} -\cos t \\ \sin t \end{pmatrix}$$

$$\begin{vmatrix} 1 & -2-r \\ 2-r & -5 \end{vmatrix} = 0 \Rightarrow r_1, r_2 = \pm 2. \Rightarrow \tilde{x}^{(1)} = \begin{pmatrix} 1 \\ 2+2i \end{pmatrix}, \tilde{x}^{(2)} = \begin{pmatrix} 1 \\ 2-2i \end{pmatrix}$$

$$\tilde{g}(t) = \begin{pmatrix} 0 \\ -1 \end{pmatrix} \cos t + \begin{pmatrix} 1 \\ 0 \end{pmatrix} \sin t.$$

We assume that $\tilde{y} = \tilde{y}(t) = \tilde{a} \tilde{t} \cos t + \tilde{b} \tilde{t} \sin t + \tilde{c} \cos t + \tilde{d} \sin t$.
Substituted into differential eqn:

$$\tilde{a} \cos t - \tilde{a} \tilde{t} \sin t + \tilde{b} \tilde{t} \cos t + \tilde{b} \sin t - \tilde{c} \sin t + \tilde{d} \cos t$$

$$= \tilde{A} (\tilde{a} \tilde{t} \cos t + \tilde{b} \tilde{t} \sin t + \tilde{c} \cos t + \tilde{d} \sin t) + \begin{pmatrix} 0 \\ -1 \end{pmatrix} \cos t + \begin{pmatrix} 1 \\ 0 \end{pmatrix} \sin t$$

$$\Rightarrow \begin{cases} \tilde{A} \tilde{c} = \tilde{a} + \tilde{d} + \begin{pmatrix} 0 \\ 1 \end{pmatrix} & \leftarrow \cos t \\ \tilde{A} \tilde{d} = \tilde{b} - \tilde{c} - \begin{pmatrix} 1 \\ 0 \end{pmatrix} & \leftarrow \sin t \\ \tilde{A} \tilde{a} = \tilde{b} & \leftarrow \tilde{t} \cos t \\ \tilde{A} \tilde{b} = -\tilde{a} & \leftarrow \tilde{t} \sin t. \end{cases}$$

$$\Rightarrow \tilde{a} = \begin{pmatrix} 1 \\ 2 \end{pmatrix}, \tilde{b} = \begin{pmatrix} 0 \\ -1 \end{pmatrix} \quad \tilde{c} = \begin{pmatrix} -1-d_1+2d_2 \\ -1-d_1+2d_2 \end{pmatrix}$$

$$\text{Let } d_1 = 0, d_2 = 0 \Rightarrow \tilde{c} = \begin{pmatrix} -2 \\ -3 \end{pmatrix}, \tilde{d} = \begin{pmatrix} d_1 \\ d_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

So,

$$\tilde{y}(t) = \begin{pmatrix} 1 \\ 2 \end{pmatrix} t \cos t + \begin{pmatrix} 0 \\ -1 \end{pmatrix} t \sin t + \begin{pmatrix} -2 \\ -3 \end{pmatrix} \cos t + \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin t.$$

General solution of the nonhomogeneous system is

$$\tilde{x} = c_1 \begin{pmatrix} 1 \\ 2+i \end{pmatrix} e^{it} + c_2 \begin{pmatrix} 1 \\ 2-i \end{pmatrix} e^{-it} +$$

$$\begin{pmatrix} 1 \\ 2 \end{pmatrix} t \cos t + \begin{pmatrix} 0 \\ -1 \end{pmatrix} t \sin t + \begin{pmatrix} -3 \\ -2 \end{pmatrix} \cos t +$$

$$\begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin t.$$

3. Numbers by variation of parameters.

$$\vec{x}' = \begin{pmatrix} 4 & -2 \\ 8 & -4 \end{pmatrix} \vec{x} + \begin{pmatrix} t^{-3} \\ -t^{-2} \end{pmatrix}, \quad t > 0$$

$$\begin{vmatrix} 4-r & -2 \\ 8 & -4-r \end{vmatrix} = 0 \Rightarrow r_{1,2} = 0. \Rightarrow \vec{q} = \begin{pmatrix} 1 \\ 2 \end{pmatrix}.$$

Thus one solution of the system is

$$\vec{x}^{(1)}(t) = \begin{pmatrix} 1 \\ 2 \end{pmatrix} e^{0 \cdot t} = \begin{pmatrix} 1 \\ 2 \end{pmatrix}.$$

The second solution is

$$\vec{x}^{(2)}(t) = \vec{q} t + \vec{q}.$$

$$A \vec{q} = \vec{q} \Rightarrow \vec{q} = \begin{pmatrix} k \\ \frac{4}{k} \end{pmatrix} = \begin{pmatrix} 0 \\ \frac{4}{1} \end{pmatrix} + k \begin{pmatrix} 1 \\ \frac{1}{2} \end{pmatrix} \quad \text{we get.}$$

$$\vec{x}^{(2)}(t) = \begin{pmatrix} 1 \\ 2 \end{pmatrix} t + \begin{pmatrix} 0 \\ \frac{4}{1} \end{pmatrix} + k \begin{pmatrix} 1 \\ \frac{1}{2} \end{pmatrix}$$

The last term is merely a multiple of the first solution $\vec{x}^{(1)}(t)$ and may be ignored. so.

$$\vec{x}^{(2)}(t) = \begin{pmatrix} 1 \\ 2 \end{pmatrix} t + \begin{pmatrix} 0 \\ \frac{4}{1} \end{pmatrix}$$

The general solution of the homogeneous system is

$$\vec{x}_h = c_1 \vec{x}^{(1)}(t) + c_2 \vec{x}^{(2)}(t).$$

$$= c_1 \begin{pmatrix} 1 \\ 2 \end{pmatrix} + c_2 \begin{pmatrix} 1 \\ 2 \end{pmatrix} t + c_2 \begin{pmatrix} 0 \\ \frac{4}{1} \end{pmatrix}.$$

Fundamental matrix is:

$$\vec{\Phi}(t) = \begin{pmatrix} 1 & t + \frac{1}{4} \\ 2 & 2t \end{pmatrix}$$

$$= c_1 \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix} + c_2 \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix} t + c_3 \begin{pmatrix} 0 \\ \frac{4}{t} \\ 0 \end{pmatrix} + \begin{pmatrix} 5 \\ 2 \\ 2 \end{pmatrix} t^{-1} - 2 \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix} t^{-2} + \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix} t^{-2}$$

$$= \begin{pmatrix} 2 & 2t \\ 1 & t + \frac{4}{t} \\ \frac{2}{9}t^{-1} - 2ht + c_1 & -2t^{-2} - 2t^{-1} + c_2 \end{pmatrix}$$

$$\Rightarrow \tilde{x} = \tilde{A}(t) \tilde{U}(t)$$

$$\Rightarrow u_1' = -\frac{2}{9}t^{-2} - 2t^{-1} \Rightarrow u_1 = \frac{2}{9}t^{-1} - 2ht + c_1$$

$$u_1' = 4t^{-3} + 2t^{-2} \Rightarrow u_2 = -2t^{-2} - 2t^{-1} + c_2$$

$$\Rightarrow \tilde{A}(t) \tilde{U}(t) = \tilde{B}(t) \tilde{V}(t) \Rightarrow \begin{pmatrix} 2 & 2t \\ 1 & t + \frac{4}{t} \\ \frac{2}{9}t^{-1} - 2ht + c_1 & -2t^{-2} - 2t^{-1} + c_2 \end{pmatrix} \begin{pmatrix} u_1' \\ u_2' \end{pmatrix} = \begin{pmatrix} t^{-2} \\ t^{-3} \end{pmatrix}$$

4. Number 7 by und. method.

$$\tilde{x}' = \begin{pmatrix} 4 & 1 \\ 1 & 1 \end{pmatrix} \tilde{x} + \begin{pmatrix} -1 \\ 2 \end{pmatrix} e^t$$

using ~~sturm-liouville~~ undetermined coefficients

$$\tilde{g}(t) = \begin{pmatrix} -1 \\ 2 \end{pmatrix} e^t$$

~~Assume that~~ when $r_1 = -1$,

$$\cancel{\tilde{x}(t) = \tilde{g}(t)} = \begin{pmatrix} 2 \\ 2 \end{pmatrix} e^t \Rightarrow \tilde{g}'' = \begin{pmatrix} -1 \\ -1 \end{pmatrix}$$

when $r_2 = 3$,

$$\begin{pmatrix} -2 & 1 \\ 4 & -2 \end{pmatrix} \begin{pmatrix} g_1 \\ g_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \Rightarrow \tilde{g}^{(2)} = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

general solution of the homogeneous equation is:

$$\tilde{x} = c_1 \begin{pmatrix} 2 \\ -1 \end{pmatrix} e^{-t} + c_2 \begin{pmatrix} 1 \\ 2 \end{pmatrix} e^{3t}$$

Assume that

$$\tilde{x}^*(t) = \tilde{u}(t) = \tilde{a} e^t + \tilde{b}$$

substituted into differential eqn,

$$\tilde{a} e^t = \tilde{A}(\tilde{a} e^t + \tilde{b}) + \begin{pmatrix} -1 \\ 2 \end{pmatrix} e^t$$

$$\Rightarrow \tilde{a} = \tilde{A} \tilde{a} + \begin{pmatrix} -1 \\ 2 \end{pmatrix}$$

$$\begin{cases} \tilde{a} = \tilde{A} \tilde{a} \\ 0 = \tilde{A} \tilde{b} \end{cases}$$

$$\Rightarrow \tilde{a} = \begin{pmatrix} -2 \\ 4 \\ 1 \end{pmatrix}$$

$\Rightarrow \tilde{a} = \begin{pmatrix} -2 \\ 4 \\ 1 \end{pmatrix}$ particular solution is

$$\tilde{x}^* = \begin{pmatrix} -2 \\ 4 \\ 1 \end{pmatrix} e^t$$

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hence, the general solution of the nonhomogeneous system

$$\vec{u} = c_1 \begin{pmatrix} -1 \\ 2 \end{pmatrix} e^{-t} + c_2 \begin{pmatrix} 2 \\ 1 \end{pmatrix} e^{3t} + \begin{pmatrix} \frac{1}{4} \\ -2 \end{pmatrix} e^t$$

5. Use your general solution for section 7.9 numbers, determine the solution if $\vec{x}(0) = \begin{bmatrix} 0 \\ 4 \end{bmatrix}$.

$$\vec{x}(0) = c_1 \begin{pmatrix} 1 \\ 2 \end{pmatrix} + c_2 \begin{pmatrix} 1 \\ -2 \end{pmatrix} + \begin{pmatrix} -3 \\ -2 \end{pmatrix} = \begin{pmatrix} 0 \\ 4 \end{pmatrix}$$

$$\Rightarrow \begin{cases} 2c_1 + 2c_2 - 3 + 1(c_2 - c_2) = 4 \\ c_1 + c_2 - 2 = 0 \end{cases}$$

$$\Rightarrow \begin{cases} c_1 = 1 - \frac{2}{3} \\ c_2 = 1 + \frac{2}{3} \end{cases}$$

$$\Rightarrow \text{solution: } \vec{x} = \left(1 - \frac{2}{3}\right) \begin{pmatrix} 1 \\ 2 \end{pmatrix} e^{2t} + \left(1 + \frac{2}{3}\right) \begin{pmatrix} 1 \\ -2 \end{pmatrix} e^{-2t} + \begin{pmatrix} 1 \\ 2 \end{pmatrix} t \cos t + \begin{pmatrix} 0 \\ -1 \end{pmatrix} t \sin t + \begin{pmatrix} -3 \\ -2 \end{pmatrix} \cos t + \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin t$$

7.

characteristic eqn is:

$$\frac{d^2 T}{dx^2} - m^2 (T - T_\infty) = 0 \Rightarrow \frac{d^2 T}{dx^2} - m^2 T = -m^2 T_\infty$$

$$r^2 - m^2 = 0 \Rightarrow r = \pm m$$

General solution of the homogeneous eqn is:

$$T_h(x) = C_1 e^{mx} + C_2 e^{-mx}$$

Assuming $T^* = a$ (a is a constant) is the particular solution of the nonhomogeneous eqn. substituting it into $\frac{d^2 T}{dx^2} - m^2 T = -m^2 T_\infty$, we obtain,

$$a = +T_\infty \Rightarrow T^* = T_\infty$$

Hence, the general solution of the nonhomogeneous eqn is-

$$T(x) = T_h(x) + T^* = C_1 e^{mx} + C_2 e^{-mx} + T_\infty$$

$$\begin{cases} T(0) = T_b \Rightarrow T_b = C_1 + C_2 + T_\infty \Rightarrow C_1 + C_2 = T_b - T_\infty \\ \lim_{x \rightarrow \infty} T(x) = T_\infty \Rightarrow C_1 = 0 \text{ (suppose } m > 0) \end{cases}$$

$$\Rightarrow C_2 = T_b - T_\infty$$

$$\Rightarrow T(x) = (T_b - T_\infty) e^{-mx} + T_\infty \quad (m > 0)$$

$$\left. \frac{dT}{dx} \right|_{x=0} = -m(T_b - T_\infty) e^{-mx} \Big|_{x=0} = -m(T_b - T_\infty)$$